

A Heuristic Approach for Solving the Cubic Monotone 1-in-3 SAT Problem

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Abstract— The present paper proposes a heuristic approach to solve a variant of the satisfiability problem (SAT) , namely the exact 3-satisfiability problem (X3SAT) which is known to remains NP-complete when restricted to expressions where every variable has exactly three occurrences, even in the absence of negated variables (Cubic Monotone 1-in-3 SAT Problem). Firstly, this problem is converted into an equivalent system of linear equations over binary variables, then it is solved using a dynamic programming heuristic based on Das algorithm requiring $O(n^4)$ time, for input formulas over n variables. Finally, a Matlab code implementation is provided.

Keywords—X3SAT, Cubic Monotone 1-in-3 SAT Problem, NP-complete, dynamic programming, heuristic

I. INTRODUCTION

The propositional satisfiability problem (SAT) is one of the first problems that have been proven to be NP-complete [1]. The present paper is devoted to solve a variant of SAT, namely the exact 3-satisfiability problem (X3SAT) which is known to remains NP-complete for expressions where every variable has exactly three occurrences, even in the absence of negated variables (Cubic Monotone 1-in-3 SAT Problem) [2] [9].

XSAT and X3SAT have been recently investigated in [3, 4, 5, 6]. However the first breakthrough result [7] dates back to the year 1980 and provides an algorithm deciding XSAT in $O(2^{0.2441n})$ time, for input formulas over n variables. This bound has been the best known until 2003, then it has been improved to $O(2^{0.2325n})$ [8]. The best known result for unweighted X3SAT provides a solution in $O(2^{0.1379n})$ time [8].

In the present paper, the Cubic Monotone 1-in-3 SAT problem is firstly converted into an equivalent system of linear equations over binary variables, then it is solved using a dynamic programming heuristic approach in $O(n^4)$ time, based on Das algorithm [10].

II. PRELIMINARIES

A literal is a Boolean variable $a \in \{0, 1\}$ or its negation \bar{a} . A clause C is the disjunction of different literals and is represented as a literal set. A k -clause is a clause that contains exactly k literals. A CNF formula F is a conjunction of different clauses and is represented as a clause set. A k -CNF formula is a formula that contains only clauses of a maximum length k . For a given formula F (resp. clause C), we denote the set of contained variables by $V(F)$ (resp. $V(C)$). Similarly, $V(l)$ denotes the underlying variable of a literal l . $pol(l)$ denotes the polarity of a literal in a fixed clause of a formula. By $V^+(F)$ (resp. $V^-(F)$) we denote the set of all variables occurring positive (resp. negated). We call a variable (resp. a literal corresponding to it) unique if it occurs in the formula only once. We distinguish between the length of a formula F and the number of its clauses $|F|$. Let CNF denote the set of all formulas and let CNF^+ denote the set of positive monotone formulas, i.e., each clause contains only unnegated variables. Given a formula F and a variable a , the formula $F[a \leftarrow 1]$ (resp. $F[a \leftarrow 0]$) is obtained from F by setting the value of a to 1 (resp. 0).

The exact 3-satisfiability problem (X3SAT) asks in its decision version, whether there exists a truth assignment $t : V(F) \leftarrow \{0, 1\}$, setting exact one literal to 1 in each clause of F . We call such an assignment t an x-model, and we denote with $X3SAT$ the set of all exact satisfiable 3-CNF formulas. In the search version of X3SAT one has to decide whether $F \in X3SAT$, and in the positive case to find an x-model of F . X3SAT restricted to expressions where every variable has exactly three occurrences, without negated variables is called Cubic Monotone 1-in-3 SAT Problem [9].

The rest of this paper is organized as follows; in the next section, proposition 1 establishes the equivalence between the Cubic Monotone 1-in-3 SAT problem, and a system of linear equations over binary variables. Section 4 proposes a dynamic programming heuristic based on Das algorithm [10] for solving this system. Section 5 provides some examples to illustrate the effectiveness of this approach. Finally, conclusion of the paper is summarized in Section 6.

III. METHODOLOGY

Proposition 1:

Finding an x -model of $F \in$ Cubic Monotone 1-in-3 SAT problem is equivalent to solve the system of linear equations $Ax=b$, over binary variables $x \in \{0, 1\}^n$,

$\{0, 1\}^n$, where A is the $n \times n$ matrix defined by:

$A_{ij}=1$ if literal j appears in clause i

$A_{ij}=0$ otherwise

and b is the n vector $b=(1, \dots, 1)$.

Proof:

Clearly, x is a model of $F \in$ Cubic Monotone 1-in-3 SAT problem is equivalent $\forall i=1 \dots n \sum_{j=1 \dots n} A_{ij}x_j=1$,

which is equivalent

to $Ax=b$, over $\{0, 1\}^n$

Notice that $F \in$ Cubic Monotone 1-in-3 SAT problem implies that the number of clauses $m=n=3p$, where p is an integer. Indeed: $Ax=b$ implies that $\|Ax\|^2=\|b\|^2$,

Let $x=\sum_{j \in J} \varepsilon_j$ where $J=\{j \in \{1, \dots, n\} | x_j=1\}$ and $(\varepsilon_j)_{j \in \{1, \dots, n\}}$ is the canonical basis of R^n .

Then $Ax=A\sum_j$ where A_j is the j^{th} column of A matrix.

$J \in j$

Then $\|Ax\|^2=\|\sum_{j \in J} A_j\|^2=m$

Since $\forall i, j \in J, x_i x_j=0$ because $A\sum_j = b$ and $\|A_j\|^2=3$

$J \in j$

Then necessarily $3|J|=m=3p$ where $p=|J|$

On the other hand, let N_1 be the number of ones of A matrix.

Since $F \in$ Cubic Monotone 1-in-3 SAT, if we count row by row then we obtain $N_1=3m$, and if we count column by column, then we obtain $N_1=3n$.

Thus $m=n=3p$.

Proposition 2:

The system of linear equations $Ax=b$, over binary variables $x \in \{0, 1\}^n$ can be solved using the following heuristic based on Das algorithm [10] :

Input: $n, A, b=(1, \dots, 1)$

Output: $x \in \{0, 1\}^n$

$B=b'$

FOR $j=n$ **downto** 1 **DO**

$C=B-A(:,j)$

$A(:,j) \leftarrow \text{NIL}$

$e0=\text{norm}(A^*(A^{**}B)-B)$

$e1=\text{norm}(A^*(A^{**}C)-C)$

IF $e0 < e1$ **THEN** $x(j) \leftarrow 0$

ELSE $x(j) \leftarrow 1$

$B \leftarrow C$

END IF

END FOR

IF $Ax=b$ **THEN** “ x is a solution of the system”

END IF


```
0000010000100000000000100000  
0000000000000010010001000000  
1000100000000001000000000000  
1000100000001000000000000000  
0100100000000001000000000000  
0011001000000000000000000000  
0001000000000100100000000000  
0000000000000001000010000100  
0000001000000000010000000100  
0000000000001010000000000100  
0100000000000001000100000000  
0100000000000000100000001000
```

solution found:

$x = (111001000000011000010010010)$

Example 3

n=24

$$F = (x_{21} \vee x_{16} \vee x_7) \wedge (x_{22} \vee x_{19} \vee x_{14}) \wedge (x_{22} \vee x_9 \vee x_{15}) \wedge (x_3 \vee x_{10} \vee x_5) \wedge (x_{20} \vee x_{18} \vee x_{17}) \wedge (x_{22} \vee x_{20} \vee x_{14}) \wedge (x_1 \vee x_3 \vee x_{13}) \wedge (x_{23} \vee x_{21} \vee x_{24}) \wedge (x_9 \vee x_8 \vee x_{19}) \wedge (x_6 \vee x_{24} \vee x_{23}) \wedge (x_9 \vee x_{17} \vee x_{18}) \wedge (x_{20} \vee x_{15} \vee x_3) \wedge (x_{14} \vee x_2 \vee x_{19}) \wedge (x_{16} \vee x_{15} \vee x_6) \wedge (x_{18} \vee x_1 \vee x_{21}) \wedge (x_{13} \vee x_{17} \vee x_8) \wedge (x_7 \vee x_4 \vee x_{23}) \wedge (x_{16} \vee x_{24} \vee x_5) \wedge (x_{12} \vee x_2 \vee x_{13}) \wedge (x_2 \vee x_5 \vee x_{12}) \wedge (x_{12} \vee x_4 \vee x_{11}) \wedge (x_6 \vee x_1 \vee x_8) \wedge (x_{10} \vee x_4 \vee x_{11}) \wedge (x_7 \vee x_{10} \vee x_{11})$$

A =

00000010000000100001000
000000000000010000100100
000000001000001000000100
00101000010000000000000000
000000000000000011010000
0000000000000010000010100
10100000000001000000000000
00000000000000000000000000
00000000110000000000100000
00000100000000000000000011
000000001000000011000000
001000000000001000010000
01000000000000100001000000
0000010000000011000000000
100000000000000000001001000
000000010000100010000000
00010010000000000000000000
0000100000000001000000001
01000000000011000000000000
01001000000100000000000000
00010000001100000000000000
10000101000000000000000000
00010000001100000000000000

000000100110

solution found:

Example 4

n=18

$$F = (x_4 \vee x_6 \vee x_9) \wedge (x_7 \vee x_{15} \vee x_{18}) \wedge (x_3 \vee x_5 \vee x_{13}) \wedge (x_7 \vee x_{18} \vee x_{12}) \wedge (x_{16} \vee x_8 \vee x_{12}) \wedge (x_{18} \vee x_{11} \vee x_{17}) \wedge (x_{13} \vee x_9 \vee x_{12}) \wedge (x_{16} \vee x_4 \vee x_8) \wedge (x_8 \vee x_{17} \vee x_2) \wedge (x_{11} \vee x_{11} \vee x_{14}) \wedge (x_{10} \vee x_5 \vee x_1) \wedge (x_{13} \vee x_{10} \vee x_2) \wedge (x_{17} \vee x_6 \vee x_5) \wedge (x_3 \vee x_6 \vee x_2) \wedge (x_{16} \vee x_{14} \vee x_{11}) \wedge (x_{15} \vee x_3 \vee x_1) \wedge (x_9 \vee x_{10} \vee x_{15}) \wedge (x_4 \vee x_7 \vee x_{14})$$

A=

000101001000000000
00000010000001001
00101000000100000
000000100001000001
000000010001000100
0000000000010000011
000000001001100000
000100010000000100
010000010000000010
100000000010010000
100010000100000000
010000000100100000
000011000000000010
0110010000000000000
000000000010010100
1010000000000010000
000000001100001000
000100100000010000

solution found:

$$x = (010110000011001000)$$

Example 5

n=39

$$F = (x_{16} \vee x_{10} \vee x_{19}) \wedge (x_{20} \vee x_{16} \vee x_{38}) \wedge (x_3 \vee x_1 \vee x_{35}) \wedge (x_{30} \vee x_{38} \vee x_{14}) \wedge (x_{36} \vee x_{14} \vee x_{10}) \wedge (x_{38} \vee x_8 \vee x_{34}) \wedge (x_{28} \vee x_1 \vee x_8) \wedge (x_{10} \vee x_{39} \vee x_4) \wedge (x_{33} \vee x_{17} \vee x_{19}) \wedge (x_3 \vee x_{29} \vee x_{24}) \wedge (x_3 \vee x_{33} \vee x_{12}) \wedge (x_8 \vee x_7 \vee x_6) \wedge (x_{32} \vee x_{22} \vee x_4) \wedge (x_9 \vee x_{31} \vee x_{27}) \wedge (x_{35} \vee x_6 \vee x_{16}) \wedge (x_{20} \vee x_{36} \vee x_{22}) \wedge (x_{28} \vee x_1 \vee x_2) \wedge (x_{19} \vee x_{28} \vee x_{29}) \wedge (x_{39} \vee x_{25} \vee x_{36}) \wedge (x_6 \vee x_{11} \vee x_7) \wedge (x_{37} \vee x_{30} \vee x_4) \wedge (x_7 \vee x_{24} \vee x_{17}) \wedge (x_{20} \vee x_{27} \vee x_{35}) \wedge (x_{21} \vee x_5 \vee x_{24}) \wedge (x_{26} \vee x_5 \vee x_{39}) \wedge (x_{21} \vee x_{30} \vee x_{13}) \wedge (x_{27} \vee x_9 \vee x_{11}) \wedge (x_{14} \vee x_{29} \vee x_{18}) \wedge (x_{22} \vee x_2 \vee x_{18}) \wedge (x_{18} \vee x_{26} \vee x_{13}) \wedge (x_2 \vee x_{17} \vee x_{32}) \wedge (x_5 \vee x_{15} \vee x_{31}) \wedge (x_{33} \vee x_9 \vee x_{13}) \wedge (x_{26} \vee x_{37} \vee x_{31}) \wedge (x_{25} \vee x_{32} \vee x_{34}) \wedge (x_{25} \vee x_{11} \vee x_{34}) \wedge (x_{12} \vee x_{15} \vee x_{23}) \wedge (x_{21} \vee x_{23} \vee x_{12}) \wedge (x_{23} \vee x_{37} \vee x_{15})$$

A=

solution found.

$x = (100011000101100010000100101010000000110)$

V CONCLUSION AND FUTURE SCOPE

In this work, a dynamic programming heuristic approach was proposed for solving a system of linear equations $Ax=b$, equivalent to the Cubic Monotone 1-in-3 SAT Problem which is an NP-complete problem.

Future work will focus on the improvement of this method, and try to find when this problem has no solution.

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Appendix

A Matlab code implementation:

```

clear all;
p=input('input p=');
n=3*p;
aa=[];
b=[];
col=[];
for i=1:n
for j=1:n
aa(i,j)=0
end;
end;
for i=1:n
col(i)=0
end;
for i=1:n
r = randint(1,1,[1,n]);
r1=r(1);
while (col(r1)==3)
r = randint(1,1,[1,n]);
r1=r(1);
end;
r = randint(1,1,[1,n]);
r2=r(1);
while (r1==r2)| (col(r2)==3)
r = randint(1,1,[1,n]);
r2=r(1);
end;
col(r1)=col(r1)+1;
col(r2)=col(r2)+1;
r = randint(1,1,[1,n]);
r3=r(1);
if i<n
while (r3==r2)|(r3==r1)| (col(r3)==3)
r = randint(1,1,[1,n]);
r3=r(1);
end;
col(r3)=col(r3)+1;
else
r3=find(col(:)==2)
col(r3)=3
end;
a(i,1)=r1;
a(i,2)=r2;
a(i,3)=r3;
aa(i,r1)=1;
aa(i,r2)=1;

```

```

aa(i,r3)=1;
fprintf('r1( %d', i);fprintf(')= %d\n', r1);
fprintf('r2( %d', i);fprintf(')= %d\n', r2);
fprintf('r3( %d', i); fprintf(')= %d\n', r3);
end;
file_1 = fopen('a.txt','wt')
file_2 = fopen('c.txt','wt')
file_3 = fopen('s.txt','wt')
for i=1:n
for j=1:n
fprintf(' %d\n',aa(i,j));
fprintf(file_1,'%d', aa(i,j))
end;
fprintf('\n');
fprintf(file_1,'\n');
end;
for i=1:n
fprintf(file_2,'(')
fprintf(file_2,'x%d', a(i,1))
fprintf(file_2,'or')
fprintf(file_2,'x%d', a(i,2))
fprintf(file_2,'or')
fprintf(file_2,'x%d', a(i,3))
fprintf(file_2,)and')
end;
tic
b=[]
for i=1:n
b(i)=1;
end;
tic
intcon=1:n
lb=zeros(n,1)
ub=ones(n,1)
x = intlinprog(b,intcon,aa,b,aa,b,lb,ub);
toc
disp(x);
disp('TIME intlinprog');
disp(toc);
rep=input('VU')
if length(x)>0
for i=1:n
fprintf('x( %d', i); fprintf(')= %.d\n', x(i));
end;
disp('checking');
y=aa*x;
for i=1:n
fprintf('y( %d', i); fprintf(')= %.d\n', y(i));

```

```

end;
end;
%=====
tic

A=aa
B=b'
for i=n:-1:1
B1=B-A(:,i)
A(:,i)=[]
e0 = norm(A*(pinv(A)*B)-B)
e1 = norm(A*(pinv(A)*B1)-B1)
if e0<e1
x(i)=0
else
x(i)=1
B=B1
end;
end
toc
disp(x');
y=aa*x;
disp('checking ...');
disp(y');
disp(toc);
if y==b'
disp('x is solution');
disp(x');
end;
end;

```